

Appl. No.: 10/529,262
Amdt. dated January 6, 2010
Reply to Office Action of October 23, 2009

Amendments to the Specification

At page 1, please amend the first paragraph as follows:

The invention relates to a gripping device for a manipulation system comprising a robot for receiving parts and feeding a manufacturing plant with a workpiece from a readied stack of workpieces. The invention also relates to a method for operating the gripping device.